

## Content

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## 1. CAN SAE J1939

### 1.1 J1939 Interface Description

The J1939 interface uses the 29 bits CAN-ID according ISO 11898. The identifier contains the following general information:

Name	Priority	Extended data page	Data page	PDU format	PDU specific (Destination address)	Source address
Length	3 bits	1 bit	1 bit	8 bits	8 bits	8 bits
Description	Message latency for transmission, 0=high ... 7=low			To determine PGN (mid byte of PGN)	PDU Format < 240: destination address PDU Format ≥ 240: group extension	Unique address
Value	6	0	0			128

The entire frame format PDU contains the identifier (29 bits) and the data section (8 byte):

Identifier					Data Bytes (0 ...64 bits)								
Priority	PGN (18 bits)				Source address	Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
	Data page	PDU format	Destination address										

### 1.2 Address Claiming (ACL)

Dynamic address claiming is supported. The sensor starts the claiming with the default source address 128.

If an address conflict with a higher prior source address occurs, the network management will increase the source address automatically by 1 until 247 is reached. If no free source address is available, the sensor will use the null address 254 and does not actively send data onto the bus, it can only be addressed using broadcast messages..

The new claimed address is used temporary only. After power on, the default source address is 128 again.

For use in networks with fixed address assignment, the dynamic address claiming can be deactivated and the start address can be changed by the user with the command "set start address" to the desired source address (128 ... 247, see chapter 1.5 Configuration Data).

The new start address remains even after power off if using the command "Store PGN Configuration".

**1.3 Device Name / Name Field**

Data in the Name field is not changeable by the user.

Name	Value	Description
Arbitrary address capable	1 / 0	1 = Yes, 0 = No
Industry Group	0	Global
Vehicle System Instance	0	
Vehicle System	127	Non specific
Reserved	0	
Function	255	Non specific
Function Instance	0	
ECU Instance	0	
Manufacturer	851	Manufacturer ID
Identity Number	> 0	Unique No.

**1.4 PGN Default Definitions**

**1.4.1 Process Data - Message Content PGN 65450**

After the sensor has claimed a source address, the measured position values will be sent automatically with a "Proprietary B" PGN message.

It is also possible to request the process data message (Configuration PGN and Reponse PGN see chapter 1.5 and 1.6) .

The process data message PGN 65450 contains the process data Linear Position (P), Velocity (V) and Status.

	Byte 7		Byte 6		Byte 5		Byte 4		Byte 3		Byte 2		Byte 1		Byte 0	
Sensor Type	Bit 7 ... 4	Bit 3 ... 0	Bit 7 ... 4	Bit 3 ... 0	Bit 7 ... 4	Bit 3 ... 0	Bit 7 ... 4	Bit 3 ... 0	Bit 7 ... 4	Bit 3 ... 0	Bit 7 ... 4	Bit 3 ... 0	Bit 7 ... 4	Bit 3 ... 0	Bit 7 ... 4	Bit 3 ... 0
Linear PV	0x00		Status (4 bits)		Velocity (16 bits)				Linear Position (32 bits, -2 <sup>31</sup> ... (2 <sup>31</sup> )-1)							

**1.4.2 Definition of the Signals (SLOT)**

Position values:

Data length 4 Bytes (signed value)  
 Resolution 0.1 mm / bit  
 Range 0 ... B mm (B = electrical measuring length of sensor)  
 Offset 0 mm  
 Transfer Function Position [mm] = (Data \* Resolution) - Offset

Velocity values:

Data length 2 Bytes (signed value)  
 Resolution 2 mm/s / bit  
 Range +/- 25 ... +/-1000 mm/s  
 Transfer Function Velocity [mm/s] = (Data \* Resolution)

**1.5 Configuration Data - Parameter Mode PGN 61184 + Source Address**

The reading and writing of parameters and the triggering of defined actions is done by Configuration PGN 61184.

The PGN includes the sensor source address in the last byte for a peer-to-peer communication.

Each configuration operation is answered with a ACK response.

**1. Index 1: Configuration**

Name	Range	Default	Size	Read Write	Description
Preset [mm]	-2 <sup>31</sup> ... (2 <sup>31</sup> )-1	0	32 bits	rw	Position offset Positive or negative values, 1 bit = 0,1 mm A new written offset will be valid immediately.
Filter average	000 ... 111 (2 <sup>n</sup> , n = 0 ... 7)	0	3 bits	rw	Value count for average filter (moving average function for position and speed calculation) 0: moving average function off 000 ... 111: moving average over 2 <sup>n</sup> values (n= 1 ... 7) A new written filter average will be valid immediately.
Arbitrary address capable	0, 1	0	1 bit	rw	0: Dynamic address claiming 1: Dynamic address claiming deactivated, fixed source address has to be set ("set start address") A new written value is not effective before reboot !

Name	Range	Default	Size	Read Write	Description
Baud rate [kBaud]	0, 1	0	1 bit	rw	Transmission rate 0: 250 kBaud 1: 500 kBaud A new written baud rate is not effective before reboot !
Transmit mode	0, 1	0 (Timer)	1 bit	rw	0 = Timer: process data is sent cyclically with the selected transmission repetition mode 1 = Request: process data is only sent after a remote request Event triggered transmission of process data is not supported. A new written transmit mode will be valid immediately.
Transmit cycle	00, 01, 10, 11	10 (50 ms)	2 bits	rw	00 = 10 ms 01 = 25 ms 10 = 50 ms 11 = 100 ms A new written transmit cycle will be valid immediately.
Set start address	128 ... 247	-	8 bits	rw	Address claiming: desired start address can be set

To write parameters, the 8 data bytes must contain the complete configuration (Byte 0 to Byte 7).  
 Newly written parameters are stored non volatile with the defined action "Store Configuration".

Programmable Parameters	Index	Basic Configuration								Interface Configuration																
		Byte 0 Bit 0...7	Byte 1 Bit 0...7	Byte 2 Bit 0...7	Byte 3 Bit 0...7	Byte 4 Bit 0...7	Byte 5								Byte 6								Byte 7 Bit 0...7			
Preset Position (Offset)	1	-2 <sup>31</sup> ... (2 <sup>31</sup> )-1																								
Filter Average	1									000...111																
Arbitrary address capable	1																									0/1
Switch Baudrate	1																									0/1
Transmit Mode	1																									0/1
Transmit Cycle	1																	00,01,10,11								
Set Start Address	1																									128 ... 247

## 2. Index 0: Trigger flags

To trigger a defined action, the 8 data bytes have to contain the following trigger flags in index 1 byte 1:

Defined actions	Index	Trigger Flags								empty
		Byte 1								
0: no action      1: execute										Byte 2 .. 7
Store PGN Configuration	0	0/1								
Reset of Status Bits	0	0/1								
Sensor reboot (like Power OFF/ON, wait 200 ms until further actions)	0		0/1							
Factory Reset to default configuration	0			0/1						
Read Temperature	0							0/1		
Read Configuration PGN	0								0/1	

Important Note:

- Only one trigger flag can be set in each operation! If more than one trigger flag is set, there is no action executed.
- If the trigger flag "Read Configuration PGN" is set, it is answered by the PGN Response "Configuration"
- If the trigger flag "Read Temperature" is set, it is answered by the PGN Response "Temperature"

### 1.6 Response PGN 65452

Each configuration operation is answered with a ACK response or with the requested data (actual used configuration and temperature) by Response PGN 65452 (8 bytes).

	Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
Acknowledge ACK	0x00	0x00	0x00	0x00	0x00	0x00	0x00	0x00
Configuration	Index	Basic Configuration					Interface Configuration	
Temperature	Temperature		0x00	0x00	0x00	0x00	0x00	0x00

**1.6.1 Definition of the additional Variables (SLOT)**

Temperature values (Internal Chip Temperature):  
 Data length 2 Byte  
 Resolution 1°C / bit  
 Data Range -200 ...+200°C

**1.7 Request Commands**

In the sensor, requests are implemented for Name Identification, Process Data Message, Software Identification (firmware version) and Component Identification (serial number).

**SA:** Sensor Source Address                      **MA:** Master Source Address

**1.7.1 Name Identification PGN 60928 0x00EE00**

Request

COB-ID	Read/ Transmit	Size	Data							
			Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x00EASAMA	Rx	3 Bytes	0x00	0xEE	0x00	-	-	-	-	-

Name Identification

COB-ID	Read/ Transmit	Size	Data							
			Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x18EEFFSA	Tx	8 Bytes	Identity number (21 bits)	Identity number (21 bits)	Identity number (21 bits) / Manufacturer Code (11 bits)	Manufacturer Code (11 bits)	ECU Instance (3 bits) / Function Instance (5 bits)	Function (8 bits)	Reserved (1 bit) / Vehicle System (7 bits)	Vehicle System Instance (4 bits) / Industry Group (3 bits) / Arbitrary Address Capable (1 bit)

**1.7.2 Process Data Message PGN 65450 0x00FFAA**

Request

COB-ID	Read/ Transmit	Size	Data							
			Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x00EASAMA	Rx	3 Bytes	0xAA	0xFF	0x00	-	-	-	-	-

Process Data Message: see chapter 1.4.1

COB-ID	Read/ Transmit	Size	Data							
			Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x18FFAASA	Tx	8 Bytes	Linear Position				Velocity		Status	0x00

**1.7.3 Software Identification PGN 65242 0x00FEDA**

Request

COB-ID	Read/ Transmit	Size	Data							
			Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x00EASAMA	Rx	3 Bytes	0xDA	0xFE	0x00	-	-	-	-	-

Software Identification

COB-ID	Read/ Transmit	Size	Data							
			Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x18FEDASA	Tx	8 Bytes	Major SW version	Minor SW version	Patch SW version	Configuration 0x00	Product code		0x00	0x00

Product code: 0x1020: TM1 series

**1.7.4 Component Identification PGN 65259 0xFEED00**

Request

COB-ID	Read/ Transmit	Size	Data							
			Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x00EASAMA	Rx	3 Bytes	0xEB	0xFE	0x00	-	-	-	-	-

Component Identification

COB-ID	Read/ Transmit	Size	Data							
			Byte 0	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	Byte 7
0x18FEEDSA	Tx	8 Bytes	Serial number (xxxxxx batch no. + yyy consecutive number, same B/N as on product label)				0x00	0x00	0x00	0x00

**1.8 Diagnosis**

**1.8.1 Process Data in Error Case**

Position value: HEX 0x7FFFFFFC  
 Velocity value: 0

**1.8.2 Sensor Status**

The sensor status is flagged in first 4 bits of Byte 6.  
 A flag is set if an error or warning has occurred since the last reboot or flag reset.  
 Caution: please be aware that the error flags are once set, they are not being reset automatically !

Sensor Data	Byte 6			
	Bit 0	Bit 1	Bit 2	Bit 3
	Internal system error	Position marker missing or out of signal range	Position marker above / below measuring range	Not used
Normal functionality, all values are valid	0	0	0	0
Normal functionality, all values are valid (warning)	0	0	1	0
Error	1	1	0	0

**1.8.3 Manufacturing Mode**



If the sensor is out of function (no data frames transmitted) and a single boot-up message with a non-extended data frame and data = 0 came up, the sensor is in manufacturing mode. This mode can be left by power off-on.

**1.9 Network Termination**

Optionally, models with internal 120 Ω network termination resistor inside the sensor are available on request.

**1.10 Abbreviations**

ACL	Address Claiming
CAN	Controller Area Network
Ch	Channel
MA	Master Address
P	Position
PD	Process Data
PDU	Process Data Unit
PG	Parameter Group
PGN	Parameter Group Number
rw	Read Write
ro	Read only
SLOT	Scaling, Limit, Offset and Transfer Function
SA	Source address
V	Velocity

**1.11 Document Changes**

Revision	Changes	Date	Who
V00	First preliminary edition	12.02.21	VM/mm
V01	1.8.2 Byte 6 was Byte 7	05.03.21	VM/mm
V02	1.8.3 Manufacturing Mode added	17.05.21	VM/mm