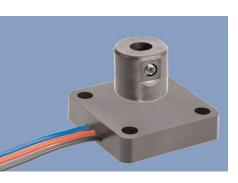


NOVOHALL Angle Sensor touchless technology transmissive

Series RFA4000 analog





Special features

- touchless technology, magnetic measurement
- enables for transmissive measurements
- electrical range up to 360°
- simple mounting
- lateral magnet offset up to ±3 mm
- protection class IP67 / IP69k
- single and redundant versions
- unlimited mechanical lifetime
- resolution 12 bit
- independent linearity ±0.5 %
- very favourable price/performance ratio
- extremely flat design 30x30x7mm³

The sensor utilizes the orientation of a magnetic field for the determination of the measurement angle. Therefore, a magnet is attached to the rotating shaft. The magnetic field orientation is captured with an integrated circuit. An analogue output signal represents the calculated angle.

The extreme miniaturization of the sensor enables the application also in very small installation spaces. The housing is made of high grade temperature-resistant plastic material. The sensor is totally sealed and therefore is not sensitive to dust, dirt or moisture.

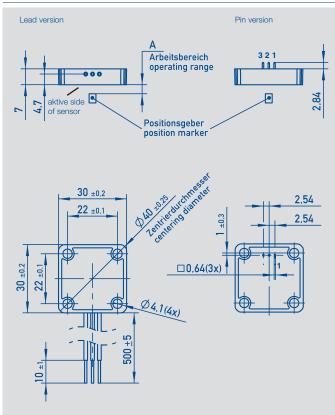
The two-part design of the sensor Series RFA and its position marker offers the customer maximal variability when mounting the sensor. The absence of shaft and bearing makes the assembly insensitive for customer application tolerances.

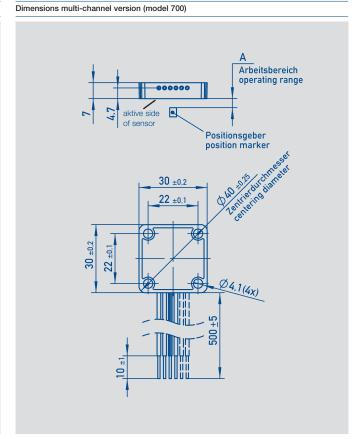
Measurements can be made transmissively through various (non-magnetic) materials.

Electrical connection is made via lead wires.

Description	
Housing	high grade, temperature resistant plastic
Electrical connections	lead wires AWG 20 (0.5 mm ²) alternative soldering pins for PCB mounting

Dimensions one-channel version (model 600)

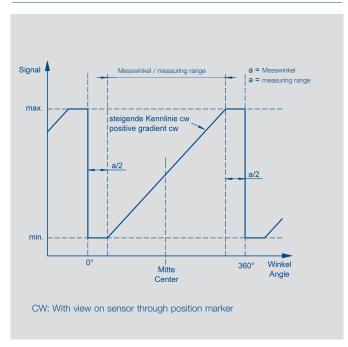




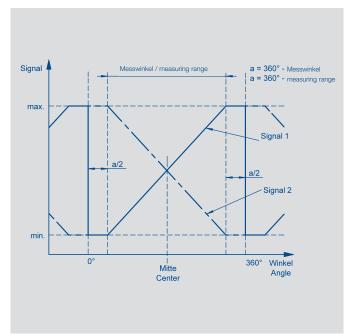
Wire colors / Pin assignment				
Signal	color	Pin No.		
Supply voltage	Red	2		
GND	Black	3		
Signal output	Blue	1		

Wire colors assignment			
Signal	Color		
Supply voltage	Red		
GND	Black		
Signal output	Blue		
Supply voltage 2	Red / white		
GND 2	Black / white		
Signal output 2	Blue / white		

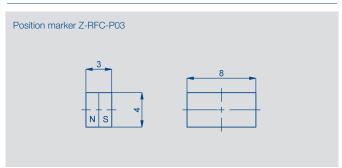
Output characteristic single (model 600)

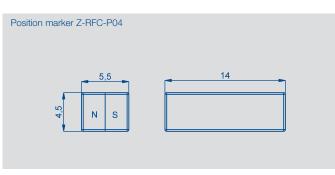


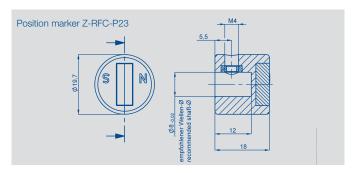
Output characteristics redundant (model 700)



Position marker examples







Technical Data and further position markers see separate data sheet.

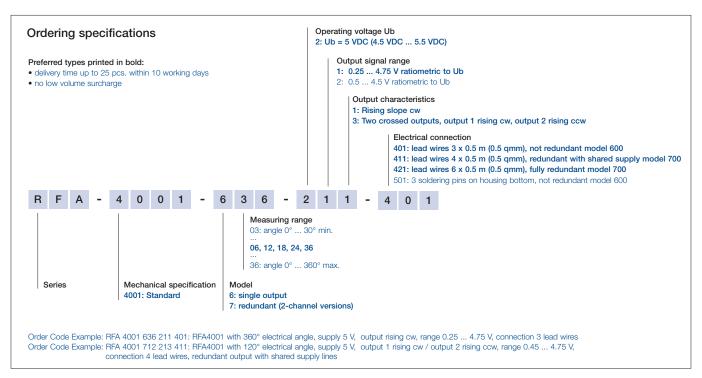
Type designations	RFA-4001	
Mechanical Data		
Dimensions	see dimension drawing	
Mounting	with 4 M4 screws (not included)	
Mechanical travel	360 continuous	0
Maximum operational speed	unlimited	min ⁻¹
Weight	ca. 10	g
Electrical Data		
Supply voltage Ub	5 ±0.5	VDC
No-load supply current	typ. 15 (typ. 8 on request) per channel	mA
Reverse voltage	yes, only supply lines	
Short circuit protection, vs. GND and +Ub	yes	
Measuring range	0 30 up to 0 360, in 10° steps	۰
Number of channels	1/2	
Update rate	5000 typ.	measur./s
Resolution	12 bit	
Repeatability	0.1	•
Independent linearity	≤ 0.5 of signal range	%
Output signal	ratiometric to Ub	,,,
Catput digital	0.25 V 4.75 V	
	0.5 4.5 V	
	(load ≥1 kΩ)	
TC at stroke angle 30 up to 170° TC at stroke angle 180 up to 360°	typical 100 typical 50	ppm/K ppm/K
Insulation resistance (500 VDC)	≥ 10	ΜΩ
Cross-section lead wires	0.5	mm ²
Environmental Data	0.5	111111
Temperature range	-40+125	
	52000	Hz
Vibration (IEC 60068-2-6)	A _{max} = 0.75	mm
	$a_{\text{max}} = 20$	g
Shock (IEC 60068-2-27)	100 (6 ms)	g
Life	mechanical unlimited	
MTTF	424 (single)	years
	330 (redundant with shared supply)	years
- (CIN EN 20500)	266 (fully redundant)	years
Protection class (DIN EN 60529)	IP67 / IP69k	
EMC compatibility	ISO 11452-2 Interference test in Absorber chamber ISO 11452-5 Interference test Stripline CISPR 25 Emitted interference CISPR 25 Conducted emission ISO 7637-1 Transients ISO 10506 ESD components check ISO 10605 ESD Handling & Packaging	
Working distance A / magnet constant	Z-RFC-P03: A = 2 \pm 1 mm / magnet constant = 1.85 [°/mm²] Z-RFC-P04: A = 4.5 \pm 1.7 mm / magnet constant = 0.8 [°/mm²]	
Lateral magnet offset (will cause additional linearity error)	max. ±3 mm (Z-RFC-P04), max, ±1.5 mm (Z-RFC-P03) The maximum error which is caused by lateral offset between sensor and position marker may be approximated as follows:	
	Error [°] = magnet constant x (offset [mm]) ² The magnet constant depends from the position marker.	
	Example: Z-RFC-P04: magnet constant = 0.8 °/mm²; offset = 0,5 mm Error [°] = 0.8 °/mm² x (0.5 mm)² = 0,2°	

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Required accessories

Position marker Z-RFC-P03, Art.No. 005658; Position marker Z-RFC-P04, Art.No. 005659; Position marker Z-RFC-P23, Art.No. 056074 (further position markers see separate data sheet Positionmarker_rotary)

Recommended accessories

Process-controlled indicators MAP... with display.

Available on request

Cable versions
Customized connectors
Specific angle ranges /
characteristics
SPI or PWM interface
Other interfaces